Social Learning in Continuous Time: When are Informational Cascades More Likely to be Inefficient?

by

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July 22, 2006

Abstract

In an observational learning environment rational agents may mimic the actions of the predecessors even when their own signal suggests the opposite. In case early movers' signals happen to be incorrect society may settle on a common inefficient action, resulting in an inefficient informational cascade. This paper models observational learning in continuous time with endogenous timing of moves. This permits the analysis of comparative statics results. The effect of an increase in signal quality on the likelihood of an inefficient cascade is shown to be nonmonotonic. If agents do not have strong priors, an increase in signal quality may lead to a higher probability of inefficient herding. The analysis also suggests that markets with quick response to investment decisions, such as financial markets, may be more prone to inefficient collapses.

Keywords: Comparative Statics, Herding, Herd Manipulation.

We would like to thank Rabah Amir and Christophe Chamley for their assistance. This paper has been presented at the Workshop on Informational Herding Behavior 2005 arranged by the Dynamic Economic Theory Network based at the Department of Economics at the University of Copenhagen. We would like to thank the participants for their helpful comments. Responsibility for errors remains our own.

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1. Introduction

Individuals with limited information often observe other people's actions before making their own decisions. The predecessors' actions tend to contain information about their private signals concerning the state of nature. In this social learning process the individual aggregates his own private signal with information collected from his observations of others' actions. This process may lead to herd behavior where the agent follows the crowd even when his private information suggests the opposite.¹ In case early movers' signals happen to be incorrect, agents may settle on a common inefficient action, resulting in an inefficient informational cascade. Gale (1996), Chamley (2004) and Bikhchandani, Hirshleifer and Welch (1998) give extensive lists of empirical phenomena that herding behavior may explain in both financial and real markets. Examples include balance-of-payments crises, R&D investment decisions, analysts' recommendation of stocks, bank runs and managers decisions to pay dividends.² It is often argued that conformist behavior in financial and real markets may lead to sudden booms and crashes.

In seminal herding papers by Banerjee (1992) and Bikhchandani, Hirshleifer and Welch (1992) and Welch (1992) there is an exogenously determined sequence in the moves. Chamley and Gale (1994) extend the literature to allow for endogenous timing of moves. Each agent has an incentive to wait in order to observe the actions of other players. However if everyone were to wait, the agent would rather move early in order to avoid costs of delay. Hence the timing decision is strategic. Chamley and Gale prove the existence of herd behavior with endogenous timing and characterize the equilibrium.

¹An informational cascade implies herding behavior. See Smith and Sørensen (2000) for the distinction.

²There are a wide variety of markets where herding may arise. For instance, see Scharfstein and Stein(1990), Welch(1992), Devenow and Welch (1996), Avery and Zemsky(1998), Welch (2000), Chari and Kehoe (2003), Chamley (2003) for analysis of herd behavior in financial markets, Neeman and Orosel (1999) for analysis in auctions, Morton and Williams (1999) for herding in a political economy framework and Bose, Orosel and Vesterlund (2002), Choi, Dassiou and Gettings (2000), Kennedy (2002) and Levin and Peck (2005) for herding among firms.

There is a vast literature that examines the conditions under which informational cascades occur and analyzes the speed of cascade formation and the fragility of cascades.³ There are however no studies that focus on the factors that affect the likelihood of erroneous mass behaviour. This paper studies the factors that influence the likelihood of inefficient cascades, either when there is an investment boom even though the true value of the project is low (an inefficient positive cascade), or when there is an investment collapse even though the true value is high (an inefficient negative cascade). The question the paper analyzes is not whether or not there will be cascade formation but the likelihood that the cascade outcome is inefficient.

Chamley and Gale offer an ex-ante welfare analysis on the inefficiency induced by delay and observational learning. The additional advantage of analyzing the likelihood of inefficient cascades arises when there are externalities from the market to society at large. The ex-ante welfare approach includes the expected discounted payoffs of the players directly involved in the game. However, bank panics, capital flight and stock market crashes have external consequences which may induce a social planner to place a greater weight on inefficient negative cascades than an individual investor. In other markets the party designing the structure of the market may not have an incentive to weigh all market participants equally. In the IPO market, for example, the features of the market are not controlled by a central planner, but rather by the firms offering companies for public sale. These companies may try to increase the probability of a positive cascade. Results on the probabilities of inefficient outcomes are a potentially useful building block for welfare and policy analysis in markets with such external effects.

The analysis of factors that influence the likelihood of inefficient herding – the discount rate, the signal quality, the prior, the expected value of the investment project – may be important for manipulating the outcome of the social learning game. For instance, the Securities Act of 1933 and the Securities Exchange Act of 1934 were formed in hopes of preventing catastrophic crashes like Black

³See Chamley (2004) for a review of theoretical advances in the study of informational cascades.

Thursday in 1929.⁴ We would like to be able to analyse the implications of an improvement in accounting standards (signal quality) on the probability of an inefficient collapse. Likewise, we would like to know the effect of an improvement in trading technology on the probability of an inefficient outcome. This paper is the first to focus on comparative statics results for all key variables in an endogenous-timing framework.⁵ Other than the directional effects of the factors that influence the probability of inefficient herding, the magnitude of the effect may be of importance as well. For instance, in an IPO decision reducing the price decreases the probability of collapse where the IPO fails. But we would like to know what the optimal price would be.

We find that the probability of an inefficient negative cascade goes up as agents get more patient.⁶ Agents with a low rate of time preference are more inclined to wait to collect more information about the true value of the project. This conservative attitude makes inefficient negative cascades more likely. In the leading herding model of Bikhchandani, Hirshleifer and Welch (1992), inefficient negative and positive cascade probabilities go down as signal quality goes up, since early movers are more likely to take the correct action. We find that this not the case in general. While an increase in signal quality does unambiguously improve the expected utility of buyers in the market, if agents do not have strong priors an increase in the signal quality may lead to a higher probability of inefficient herding.

Our paper adapts the Chamley and Gale (1994) endogenous-timing information-revelation model of investment. The equilibrium is in the same spirit as in Chamley and Gale. However our agents

⁴Among other regulations, the act requires that investors receive financial and other significant information concerning securities being offered for public sale.

⁵In our paper, in equilibrium agents follow a critical mass. In Zhang's (1997) model with heterogenous signal quality, all imitate the one leader with the most precise signal. The probability of an inefficient cascade is then just equal to the probability of the most precise signal being incorrect.

⁶Chamley and Gale show that at *=1 only negative cascades will be inefficient. This paper extends their result to comparative statics over the full range of *.

observe others' actions in continuos time. The learning process can be approximated by a series of Brownian Motions and the familiar boundary crossing probabilities are employed to find the probabilities of inefficient positive and negative cascades. The merit of a continuous-time framework is that it enables us to approximate a closed-form solution to the probability of inefficient cascades. The cost is a number of ad-hoc assumptions on the market that will allow the model to be technically tractable.

2. Overview

In the Chamley-Gale model the higher the value of the project the more people there are with an option to invest. The project value and number of people with an option are unknown to the agents. Each agent with an investment option faces a tradeoff between investing and waiting. If the agent invests he collects the undiscounted payoff, but faces the risk of making a loss in case the true value of the project is low. If the agent waits he collects only the discounted payoff, but he can learn from others' actions. In equilibrium the agent is just indifferent and randomizes between waiting and investing. Therefore, the rate of investment each period is stochastic. The agent tries to deduce from the rate of investment each period the number of people with an option and hence the value of the project. If the expected value of the project turns negative the agent strictly prefers to wait, as does everyone else, and so the game ends with an investment collapse. If the expected value of the project becomes so high that agents strictly prefer to invest, the game ends with a sudden investment boom. Since the learning process is stochastic, the outcome may be inefficient. Even when the true value of the project is high (low), there might be an investment collapse (boom).

Here we adapt a special case of the model in which there are only two possible values of the project allowing agents' beliefs to be summarized in a single variable, the probability that the project value is high. It will be shown that a monotonic transformation of the subjective probability yields a

learning process characterized by a simple Lévy process: $w_t = w_{t-1}-a+bk_t$ where w_t denotes the transformed subjective probability and k_t is the stochastic number of buyers observed in the period and it is given by the Poisson approximation to the binomial distribution. The problem is to determine the probability that w_t crosses the upper bound (where the agent strictly prefers to invest) before the lower bound (where the agent strictly prefers to wait) resulting in an investment boom and the probability that w_t crosses the lower bound before the upper bound, resulting in an investment collapse. This is a mathematical problem that arises in a number of contexts from psychology to queuing theory and hence has been extensively studied. Nevertheless, despite its seeming simplicity no closed-form solution has been found. Hence we depart from the Chamley and Gale framework and move to a continuous-time learning setting.

For the continuous-time adaptation, we make some institutional restrictions on the market to make the model technically tractable. We have an agency which takes state-contingent orders in discrete time and processes them in continuous time. Agents are allowed to make their invest and wait orders (placed in discrete time) contingent on the continuously evolving flow of order processing. The payoffs are received at the end of the period. If the expected level of investment were constant in all periods this would result in a continuous-time process for the transformed beliefs that is identical to the evolution of queue lengths in a standard M/D/1 queue. The standard approximation for this is Brownian motion. Our learning process is then a series of one-period Brownian motions.

For tractability it is also assumed that the processing agency has a capacity limit to the number of contingent orders it can accommodate. The capacity limit helps us keep the same basic incentives as in Chamley and Gale while ensuring that information transmission stops as soon as one of the boundaries is hit. Hence we can make use of the boundary crossing probabilities for Brownian Motion to find the probability of an inefficient informational cascade.

3. Framework

The true value of the investment project is denoted by $VO\{V^H V^L\}$ where $V^H > O$ and $V^L < O V = V^H$ with prior probability q*O(0,1). The number of rational players rN is unboundedly large, r64.⁷ Players are risk neutral. They are ex-ante identical. However, only *rn* of them receive an investment option. Options are identical and indivisible. If the true value of the project is high, there are more agents with an investment option:

$$n = \bigwedge^{n} n^{H} w en V = V^{H}$$

$$\bigwedge^{L} w en V = V^{L}$$
(1)

Denote $\psi \equiv \frac{n^L}{n^H} < I$ R is a measure for signal quality. The further apart n^L and n^H, the more information the agent has about the true value of the project from the fact that he has observed the investment option in the first place. If n^L were equal to n^H, the agent who receives the investment option would not update his prior. The agent will update his prior belief more heavily as R goes down.⁸

Each agent with an investment option can give an invest order at any date T=0,1,2,... of his choice. Payoffs from the exercised options are received at the end of the time period. * O(0,1) is the common discount factor. Investment is irreversible. If the player never invests, the payoff is 0. Whether or not the player has an option is private information. Only if the option is exercised is

⁷This paper adapts the *r-fold replica* game of Chamley and Gale (1994), Section 6.

⁸In order to compare this signal quality measure to the signal quality measure in Banerjee(1992) and Bikhchandani, Hirshleifer and Welch (1992), suppose that each of the rN potential investors receive a signal about the value of the project. The signal is correct with probability p>0.5. If V=V^H then prN=rn^H get a positive signal. If V=V^L then (1-p)rN=rn^L get the positive signal. Then $\psi = (1 - p) / p$. One could easily formulate the problem in this way and the equilibrium would mirror that found here, with the agents who received a negative signal simply waiting to observe a positive cascade and then investing if and only if the true value is revealed to be V^H. Here we keep the Chamley and Gale structure in order to facilitate direct comparison.

information revealed.⁹ Each player with an option chooses to either invest now or delay. When making their decisions, players can observe the history of other players' investments.

Here the value of the project is either high or low and there is a one-to-one mapping between V and n. The restriction to only two possible project values will allow us to summarize agents' beliefs at time t about the true state of nature via the probability that the project value is high, denoted by q_i . This mapping will prove to be very convenient in eventually formulating the learning process in a linear fashion.

3 I Tradin Tec nolo Y

Agents place discrete-time state-contingent orders which get processed in continuous time. Orders are placed at the beginning of each period. They are processed randomly during the period. The exact time that an individual order is processed is distributed uniformly in the period. Payoffs on all orders processed in a period are received at the end of the period. Since information on others' actions will be arriving during the period, learning is continuous. Players are permitted to make their orders (both invest and wait orders) contingent on the flow of information. Each invest order comes with a state-contingent wait order. Investment cannot be reversed in case the invest order is already processed. Likewise each wait order comes with a state-contingent invest order.

We will eventually approximate the agents' learning process as a series of one-period Brownian Motions with absorbing boundaries. We can make use of the familiar boundary crossing probabilities only if the equilibrium is such that learning stops the first time the learning process hits either of the bounds. We introduce a limit on the capacity of the agency to process contingent orders so that the information flow ceases as soon as one of the boundaries are hit. During the interval [T T+I] if the state-contingent wait order is triggered then at most *M* invest orders are canceled. *M* is

⁹See Gossner and Melissas (2006) for a framework with cheap talk among agents.

a very large but finite number. During the interval [T,T+1), if the state of the state-contingent invest order is triggered, then at most *M*-6 of the newly triggered invest orders are processed randomly during the remainder of the period where 6 is the number of invest orders placed at the beginning of the period.¹⁰ After the description of the equilibrium strategies, the advantage of allowing for statecontingent orders and limiting the maximum capacity of the processing agency will become clear. It is discussed at the end of section 4.3.

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The quality of the analytic approximation to the cascade probabilities will be improved if we will also include copycat traders. There are K=Nrn^H people who are randomly assigned to this market and they simply imitate the probability of investment of rational traders with an investment option. The copycats are not needed for the equilibrium of model derived here. However it will be shown that the K people add noise to the information to be collected from the market. So they make it harder for the market participants to deduce the true value of the project from the observed purchases – resulting in a higher expected number of invest orders per period. In equilibrium, this will not alter the amount of information transmitted by observational learning, but it leads to a larger number of buyers required in equilibrium to transmit the same amount of information (to be discussed in Section 5.2). The larger the expected number of invest orders the better is the approximation, hence the existence of copycats improves the quality of the approximation to Brownian Motion.

¹⁰The capacity to accommodate state-contingent wait orders M does not need to be the same M as in the capacity to accommodate state-contingent invest orders M-6. They just need to be very large finite numbers. One could make the limit on contingencies dependent on how busy the agency will be in the remainder of the period: A limit of M)t where)t is the amount of time remaining in the period. This would necessitate keeping track of more notation but would not change the results.

4. Equilibrium

The focus is restricted to symmetric Perfect Bayesian Equilibria. Before describing the equilibrium strategies, let us first introduce some critical values.

4 I Critical Values

Since orders are processed in continuous time, q_t evolves in continuous time. The index of time for discrete-time decision nodes is denoted by *T*. While $t \ 0 \ u^+$ the index *T* $0 \ u$ So, at time nodes when t=T, $q_t=q_T$ Bayes' rule is assumed to describe the agents' method of updating the probabilities. At the beginning of the game, the probability that the project has a high value $q_{T=0}$, conditional on having received an investment opportunity, is given by:

$$q_{0} = \frac{\frac{rn^{H}}{rN}q^{*}}{\frac{rn^{H}}{rN}q^{*} + \frac{rn^{L}}{rN}I - q^{*})}$$
(2)

Since $\psi \equiv \frac{n^L}{n^H}$, (2) can be rewritten as,

$$q_0 = \frac{q^*}{q^* + \psi I \cdot q^*} \tag{3}$$

The game is of interest if initially the expected value of the project is positive:

$$q_0 V^H + \boldsymbol{I} - q_0 \) V^L > 0 \tag{4}$$

Otherwise each agent would strictly prefer to wait and the game would end immediately with an investment collapse.

It will be useful to introduce two critical values for the subjective probability. Define \underline{q} as the probability where the expected value of the project is zero:

$$q V^{H} + I - q) V^{L} = O$$
⁽⁵⁾

If q_t falls below q the agent strictly prefers to wait since the expected value of investment is negative. Since everyone who has not yet invested is identical they all prefer to wait and investment stops for good.

Define q as the probability where the agent is just indifferent between investing now and waiting when information about the true value of the project is to be fully revealed with certainty next period:

$$q V^{H} + I - q V^{L} = * q V^{H}$$

$$\tag{6}$$

If q_t rises above q the agent will strictly prefer to invest now. And so will all the identical players and the game ends with an investment boom where all players with an option invest. The game will be said to be *active* when $q < q_t < q$

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Let 8_{T} denote the probability that a player who has not yet exercised his option puts in an invest order at the decision node T. In the *active* phase of the game, it must be that $0<8_{T}<1$. Assume for a moment that an agent expects all people with an investment opportunity to invest this period. Then he would strictly prefer to wait to be able to learn the value of the project for sure. But so would everyone else. Hence 8_{T} ...1. Let us now consider the case where nobody invests this period, $8_{T}=0$. If nobody is expected to ever invest then no information will be revealed in the future so an individual would strictly prefer to invest since $q < q_{t}$, a contradiction. If investment will resume sometime in the future then an individual contemplating being the first future investor would strictly prefer to invest now rather than wait since then he would have the same expected value of the game as in this period, but discounted. Hence he would strictly prefer to invest now, so 8_{T} ...0, by contradiction. Hence in the *active* phase of the game, there can be no pure-strategy equilibrium, $0<8_{T}<1$. Players are just indifferent between waiting and investing now. Notice that 8_T is the endogenous rate of information flow. If 8_T were zero, no information would be revealed. If 8_T were equal to one, the number of people who invest would fully reveal information about the value of the project.

In equilibrium, the history of the game will affect players' strategies only through the subjective probability q_i and therefore $8_7=8 q_T$) While players' actions depend on the publicly observed history of the game, history could be payoff relevant for two reasons: *i*) It influences players' beliefs about the probability that the project has a high value, *ii*) As more and more people invest, the number of potential investors with unexercised options goes down and hence history could potentially alter the future flow of information. However the second argument cannot apply in equilibrium. Notice that the expected number of invest orders, either $8_T(R+N)rn^H$ when $V=V^L$ or $8_T(1+N)rn^H$ when $V=V^H$, must be finite. If it were infinite, the observation of the rate of investment in one period would reveal the true value of n, and hence V by the law of large numbers. In such a case all players would strictly prefer to wait, implying $8_T=0$, a contradiction. As r64, the population of potential investors is very large so players are essentially sampling with replacement. For any finite number of exercised options there is still an infinitely large number of potential investors. Hence the history of the game is payoff relevant only because it influences the agents' belief that the project has a high value. In order to save on notation, we will denote $8 q_T$ as 8_T .

Since agents randomize with $0 < 8_T < 1$, the level of investment each period is stochastic. As r64, the number of people putting in invest orders at a decision node is given by the Poisson approximation to the binomial distribution. The parameter of the Poisson distribution is $(rn8_T + N8_T rn^H)$, the mean number of invest orders by the investors $8_T rn$ plus the expected number of invest orders by the copycats $N8_T rn^H$. During the period these investors' orders will be processed randomly. Assuming no contingencies are triggered, the time between completed orders has the exponential distribution and the number of orders processed in any time interval t0(0,1) is distributed Poisson with parameter $(rn8_T + N8_T rn^H)$ t. The possibility of contingencies being triggered is discussed in Section 4.3.

Take any x0[0,1) and any t0(0,1-x). When $V=V^H$, the probability that k players' investments are processed during the time t given 8_T is denoted by $f^H k$; $8_T t$:

$$f^{H} k; \lambda_{\mathrm{T}}, \Delta \mathbf{t} = \stackrel{\bullet}{\bullet} \frac{e^{-I + \phi \, \lambda_{\mathrm{T}} r n^{H} \Delta \mathbf{t}} \left[I + \phi \right) \lambda_{\mathrm{T}} r n^{H} \Delta \mathbf{t} \, J^{k}}{k!}_{0} \text{ for } k \in \mathbf{Z} \cap [0 \ I + \phi \,) r n^{H}]$$

$$(7)$$

and the p.d.f. is denoted by $f^L k$; $\mathbf{8}_T \mathbf{)}t$) when $\mathbf{V}=\mathbf{V}^L$:

$$f^{L}k;\lambda_{\rm T}, \ \Delta t \) = \begin{pmatrix} \bullet & e^{-\psi + \phi \)\lambda_{\rm T}} rn^{H} \Delta t \ f \ \psi + \phi \)\lambda_{\rm T} rn^{H} \Delta t \ J^{k} \\ \hline k! \\ \bullet & 0 \qquad \text{elsewhere} \end{cases} \text{ for } k \in \mathbb{Z} \cap [0, (\psi + \phi) m^{\rm H}]$$

$$\tag{8}$$

If n^{L} were equal to n^{H} , then R=1 and the two probability density functions would collapse together. In such an extreme case the quality of the information k contains would be nil and the observation of the rate of investment would not reveal any information.

The agent tries to deduce from the number of people who invest in each period which distribution the observation comes from. Define k_{j_t} as the number of invest orders processed during the time j_t . Bayesian learning implies that at time $T+x+j_t$, when the agent observes k_{j_t} people investing, the subjective probability will evolve following:

$$q_{T+x+\Delta t} = \frac{q_{T+x} f^H k_{\Delta t}; \lambda_T \Delta t}{q_{T+x} f^H k_{\Delta t}; \lambda_T \Delta t + I - q_{T+x} f^L k_{\Delta t}; \lambda_T \Delta t}$$
(9)

Let us first assume that the institutional environment restricts the agents to only use \underline{q} and \overline{q} as their triggers for the contingent orders. In Appendix B, this assumption is relaxed. The equilibrium of the game with any finite set of possible trigger points which contains \overline{q} and \underline{q} is shown to yield the same cascade probabilities as this baseline model.

PROPOSITION 1: T e followin equilibrium strate ies support a SYmmetric Perfect BaYesian Equilibrium

a) If t e subbective probabilitY is sufficientlY low $q_T #q$ put in a wait order wit a statecontin ent invest order If in t e time interval $[T T+I] q_t q t e state-contin ent invest order is tri ered b) If t e subbective probabilitY is sufficientlY i q_Tq$ put in an invest order wit a state-

contin ent wait order If in t e time interval $[T T+I] q_i #q$ t e state-contin ent wait order is tri ered

c) If t e subbective probabilitY is $q < q_T < q$ wit probabilitY $\mathbf{8}_T$ put in an invest order wit a state-contin ent wait order If in t e time interval [T T+I] $q_t #q$ t e state-contin ent wait order is tri ered Wit probabilitY $I-\mathbf{8}_T$) put in a wait order wit a state-contin ent invest order If in t e time interval [T T+I] $q_t q t e state-contin ent invest order is tri ered

PROOF: a) By equation (5), when the subjective probability is \underline{q} , the expected value of the project is just equal to zero. All agents prefer to wait when $q_T #q$. Hence the state $q_T #q$ is absorbing. Investment stops for good. Information transmission terminates. There is no possible deviation from the equilibrium strategy that would make the agent better off. Off the equilibrium path, if in the time interval [T,T+1) new information arriving leads to an updated belief q_t \$ \overline{q} , the agent prefers to invest and the statecontingent invest order is triggered. Since r64, and only *M*-6 invest orders can be processed, the probability of an individual agent's state-contingent invest order being processed is zero.

b) When q_T \$ \overline{q} , by equation (6) the agent strictly prefers to invest now even if this period the true value of the project is to be revealed for sure. When q_T \$ \overline{q} , all with an option give invest orders. Since r64, during the time interval [T,T+1) the true value of n and hence V is revealed at once. If V=V^H the

subjective probability would remain above \overline{q} . If V=V^L, the subjective probability would drop below \underline{q} . All agents' state contingent wait orders would be triggered at once but only M of them would be able to stop investment.¹¹ The game would end with all investing except of those lucky M. Therefore, q_T \$ \overline{q} is an absorbing state as well.

When $q_T \$ \overline{q}$, an individual agent could consider the following deviation from the equilibrium strategy: Giving a wait order with a state contingent invest order. If all follow the above described equilibrium strategy, information about the true value of the project would be revealed at once, and the agent's state contingent invest order would be triggered at once. However his order would be not served in the period, since at most M-6 of the newly triggered orders are processed during the period. In equilibrium, when $q_T \$ \overline{q}$ all give invest orders, since r64 so does 6. Hence the probability of a newly triggered invest order being processed is goes to zero. Therefore a deviation would lead to one period of discounting. By equation (6) the agent would strictly prefer to follow the equilibrium strategy.

c) If the subjective probability is $q < q_T < q$, the expected value from investment is positive but the agent will also consider waiting in order to learn about the true value of the project. In equilibrium, the agent is just indifferent between investing now and waiting. See the beginning of Section 4.2 for the discussion of the non-existence of pure-strategy equilibrium.

i) The agent with an investment option who has not yet exercised his option will put an invest order at time *T* with probability 8_T If in the time interval $[T T+I] q_t$ falls below *q*, the agent would prefer to wait by equation (5). All unprocessed invest orders would convert into wait orders. Since *M* is a very large number, investment would stop for good.

ii) The agent with an investment option who has not yet exercised her option will put a wait order at time *T* with probability $(1-8_T)$. If however in the time interval $[T T+I] q_t$ rises above

¹¹Because M is a large but finite number, the probability of an individual agent's statecontingent wait order being processed is zero.

q the agent would prefer to invest. M is very large but finite. M-6 newly arrived invest orders would be processed this period. All the rest would be processed next period. At time T, the agent realizes that there is an infinitely small probability that his invest order would be processed if the state is triggered.

At this point the advantage of allowing for contingent orders should be clear: In the active phase of the game, the subjective probability evolves in continuous time within the bounds \underline{q} and \overline{q} . Because we let potential investors put in contingent orders, the game stops the first time q_t hits either of the bounds. Once either of the bounds is hit, information transmission stops. Without contingencies, within the time interval [T,T+1), the subjective probability could potentially cross one the bounds and then bounce back depending on the flow of the invest order processing since the exact timing of the processing of the individual order is a random variable. In the active phase of the game, if the process hits q all state-contingent invest orders are triggered.

If the processing agency did not have a capacity constraint, the true value of the project would be revealed at once and potentially the subjective probability could drop below \underline{q} . However the agency can process only M-6 newly triggered invest orders. So, no matter whether the true n is n^{H} or n^{L} the same number of invest orders will be processed. Therefore in the remainder of the period, the agent cannot gain further information about the true value of the project. Information flow stops the moment the subjective probability hits the upper bound. If the process hits \underline{q} , state-contingent wait orders are triggered and they get served since M is a very large number. Therefore information flow would stop.

5. Information Cascades

Agents' beliefs about the true value of the project evolve as a result of observational learning. If the subjective probability hits q before \overline{q} , the game ends with an investment collapse. If the subjective probability hits q before q, the game ends with an investment boom. We are particularly interested in the probability of inefficient cascades. The measures of interest are then the probability that the process hits q before \overline{q} when $V = V^{H}$, and the probability that the process hits q before q when $V = V^{H}$. The first is an inefficient negative cascade and the latter is an inefficient positive cascade.

While the paper will discuss both types of inefficient outcomes, notice that only inefficient negative cascades would be categorized as inefficient herding. Here agents that receive an investment option would invest if learning were not permitted, by (4). Since by definition herding is acting against one's own signal, we can talk about inefficient herding only when the crowd chooses not to invest.

5 I Transformation

In order to obtain the boundary crossing probabilities, we need to transform the problem into an equivalent problem that is tractable. Subjective probabilities evolve following (9), substitute $f^{H}(k; \mathbf{8}_{T})t$ and $f^{L}(k; \mathbf{8}_{T})t$ from (7) and (8) into (9). Cancel out *k* factorial from the numerator and denominator. Take the inverse of both the left and right hand side of the equality and subtract one from each side. Now plugging in R for $\frac{n^{L}}{n^{H}}$ yields,

$$\frac{I - q_{t+\Delta t}}{q_{t+\Delta t}} = \frac{I - q_t}{q_t} e^{I - \psi \lambda_t r n^H \Delta t} \overset{\Box}{\Box} \psi + \phi \overset{k_{\Delta t}}{\Box}$$
(10)

Taking the natural logarithm of both sides and multiplying both sides by minus one yields:

$$-ln \underbrace{\Box I - q_{+\Delta t}}_{\Box q_{+\Delta t}} = -ln \underbrace{\Box I - q}_{\Box q_{t}} = I - \psi)\lambda_{T}rn^{H}\Delta t - k_{\Delta t}ln \underbrace{\Box \psi + \phi}_{\Box 1 + \phi} = (11)$$

where k_{a_t} is distributed Poisson with the parameter $8_T I + N rn^H t$ when the true value of the project is high and it is distributed Poisson with the parameter $8_T R + N rn^H t$ when the true value of the project is low. Define a transformation w_t as:

$$w_{t} \equiv -ln \square \frac{I - q_{t}}{Q_{t}} \square$$
(12)

Notice that w_t is an increasing monotonic transformation of q_t We can rewrite (11) as:

$$w_{t+\Delta t} = \psi - I \lambda_T r n^H \Delta t + w_t - l n \frac{\Box \psi + \phi}{\Box 1 + \phi} \frac{\Box}{\Box} k_{\Delta t}$$
(13)

The transformed subjective probabilities evolve following (13), where k_{jt} is investment in **)**t.

In this model individual learning follows a stochastic process with independent increments. It is interesting to note that this process is a well-known description of individual learning in cognitive psychology. That literature looks, for example, at how people identify objects looking at pictures. In much of the literature individuals are modeled as learning through random sampling. This characterization of the learning process is then used to explain laboratory evidence on individual response times and error rates. The present paper shows that even with fully rational agents, group behavior will resemble the individual behavior of boundedly rational agents of the type used in cognitive psychology.¹²

The transformation (12) of the lower bound given by (5), of the upper bound given by (6) and of the starting point given by (3) yield :

The lower bound:
$$q Y w$$
 $w = ln - V^L - ln V^H$ (14)
The upper bound: $q Y w$ $w = ln - V^L - ln V^H - ln I - \delta$ (15)

¹²See Luce (1986) for an introduction to this literature.

The starting point: $q_0 Y w_0 \qquad w_0 = lnq^* - ln I - q^* - ln\psi$ (16) Since initially the expected value of the project is positive (4), $w < w_0$. And $w_0 < w$ examining (6) and

52 BoundarY Crossin Probabilities wit constant 8

(3) together.

The transformed subjective probabilities follow equation (13) where the error term k_{jt} is distributed Poisson with the parameter $(rn8_T + N8_T rn^H)$)*t*. Both the mean and the variance of the process depend on 8_T and hence they depend on the history of the game. They are not constant.

Now we are going to examine a different process. In this modified problem we will examine the processes described by equations (13) and (7) and (8) yet with a constant 80(0,1), implying a constant Poisson parameter. Section 5.3 will prove that the process with the endogenously-determined non-constant 8 will yield identical boundary crossing probabilities as in this modified problem with fixed 8.

With a constant 8, equation (13) implies that w_t evolves in the same way as the queue length in a standard M/D/1 queue. An M/D/1 queue has exponential arrivals, so the distribution of new customers over an interval **)***t* is Poisson, and one server who takes a deterministic amount of time to serve a customer. Here we will make use of the standard results for the queue length for heavy-traffic M/D/1 queues and approximate the evolution of w_t as a Brownian Motion¹³:

$$w_{t+\Delta t} \approx w_t + k_{\Delta t}^* \tag{17}$$

¹³See Kleinrock (1976) for a textbook derivation and Gaver (1968) for the original contribution. This is known as the "heavy-traffic diffusion approximation."A heavy-traffic queue is one in which the average arrival rate of customers is close to the capacity of the server. In queuing theory this is important for the approximation because otherwise the queue length would have a mass point at zero length. This issue does not arise here because the game will effectively end when either of the boundaries are hit. Here we have absorbing boundaries rather than the reflective boundary of a queue.

where k_{jt}^{*} is distributed normal with mean $:^{a}t$ and variance $F^{2a}t$:

 $=^{H}>0$ by Claim A1, and $=^{L}<0$ by Claim A2 in the Appendix.

It is important to emphasize the limitations of this approximation. It is a good approximation for a high expected rate of investment. This will happen with a high N (high numbers of noise traders). Keeping the rate of information flow 8 constant, an increase in N leads to a weaker drift. That is the positive drift :^{*H*} declines and the negative drift :^{*L*} increases. The higher N the less informative a single observation is about the true value of the project. Both $(F^2)^H$ and $(F^2)^L$ go down with an increase in N, keeping 8 constant. Each observation has less informational content, hence beliefs don't get updated as much. Therefore keeping 8 constant, an increase in N would make agents strictly prefer to wait. Since in equilibrium agents are just indifferent between investing and waiting, a higher N must be associated with a higher 8. Moreover as $q_T \rightarrow \overline{q}$, $\lambda_T rn \rightarrow \infty$. Hence for a given)*t* and q_T , there is a N that will yield a high enough Poisson parameter $(rn8_T + N8_T rn^H)$)*t* so that the normal approximation is reasonable. For any finite N there will be a range $q_T \in (\underline{q}, \tilde{q}]$ where the approximation is not reasonable. Notice however that 8 only changes at $t \in \mathbb{Z}$, so by increasing N and hence decreasing \tilde{q} we can make the probability of ever encountering $q_T \in (\underline{q}, \tilde{q}]$ small. Brownian Motion also requires that the normal approximation holds as **)***t*60. Just as in queuing theory there is no set of parameters where this is the case, hence as in queuing theory it will always be an approximation.

The standard boundary crossing probabilities for Brownian motion yield the following results.¹⁴ *i)* ProbabilitY of *ittin* w before w w en $V=V^H$

$$Prob \ \underline{w} \ before \ \overline{w} \ | V = V^H \) = I - \frac{1}{2} \left[e^{\frac{2J^H w}{(\sigma^2)^H}} - e^{\frac{2J^H w}{(\sigma^2)^H}} - \frac{2J^H w}{(\sigma^2)^H} - \frac{2J^H w}{(\sigma^2)^H} - \frac{2J^H w}{(\sigma^2)^H} - \frac{2J^H w}{(\sigma^2)^H} \right]$$
(20)

Multiply the numerator and the denominator of (20) by $exp \begin{bmatrix} 2J & \underline{w} \\ \sigma^2 & \underline{w} \end{bmatrix}^{-1}$. Plug in Equations (18), (14), (15) and (16) for $w w w_0 = H^{-1}$ and $F^2 H^{-1}$:

Prob
$$\underline{w}$$
 before $\overline{w}|_{V=V}^{H}|_{I=I} = I - \frac{\Box}{\Box} I - e^{2\varphi^{H} \sum_{\leq} \ln I - q^{*} - \ln q^{*} + \ln \psi - \ln V^{H} + \ln - V^{L}} \sum_{q = \Box} \Box$

$$\Box I - e^{2\varphi^{H} \ln I - \delta} \Box$$
(21)

where $\varphi^{H} = \frac{J^{H}}{\sigma^{2}}$. By Claim A1 in Appendix A, $z^{H} > 0$. So $n^{H} > 0$.

ii) ProbabilitY of ittin w before w w en $V = V^{L}$:

$$Prob \ \overline{w} \ before \ \underline{w} \ | V = V^L \) = \square \ e^{(\sigma^2)^L} - e^{\frac{-2J^L w_0}{(\sigma^2)^L}} \square \ \square \ \square \ e^{(\sigma^2)^L} - e^{(\sigma^2)^L} \square \ (22)$$

Plug in (19), (14), (15), (16) into (22):

Prob
$$\overline{w}$$
 before $\underline{w} | V = V^L \rangle = \frac{I - e^{2\varphi^L \sum_{\leq}^{V} \ln I - q^* \cdot) - \ln q^* + \ln \psi - \ln V^H \cdot) + \ln - V^L \cdot \gamma_f}{I - e^{2\varphi^L \ln I - \delta)}}$ (23)

¹⁴See for example Karlin and Taylor (1975) for the derivation.

where $\varphi^L \equiv \frac{J^L}{\sigma^2}$. By Claim A2 in Appendix A, $z^L < 0$. So $n^L < 0$.

Before proceeding to the next subsection it is crucial to notice that n^{H} and n^{L} are independent of 8, from (18) and (19). While an increase in 8 leads to an increase in :, it also leads to an increase in F^{2} . And these two effects counterbalance each other in the determination of the boundary crossing probabilities. Hence these probabilities are independent of 8.

53 Inefficient Cascade Probabilities for t e Ori inal Problem

PROPOSITION 2: T e boundarY crossin probabilities of t e ori inal problem are equal to t e boundarY crossin probabilities found usin a Brownian Motion 21) and 23) of t e modified problem

Proof:

In the actual learning process, the 8 is updated at each decision node. The process is a series of one period Brownian Motions. The boundary crossing probabilities for this process can be reconstructed iteratively using Lemma B1 in Appendix B. Starting with the Brownian Motion with absorbing boundaries defined in (14) and (15) and the starting point given by (16), create a process where the parameter λ changes to λ' (which is stochastic) at *T*=1 and stays constant thereafter. From Lemma B1, this new process has the same transition probabilities as the original process. Iterating this argument yields the result.

Denote the probability of an inefficient negative cascade by *Prob INC*) which is equal to the probability that the process hits \underline{q} before \overline{q} when $V = V^{H}$. By Propostion 2, *Prob INC*) is given by equation (21).

Prob IPC) denotes the probability of an inefficient positive cascade and it is the probability that the process hits *q* before *q* when $V = V^L$. By Proposition 2, *Prob INC*) is given by equation (23).

6. Comparative Statics

6 I T e Prior Expected Value

When there is potentially a lot to gain ($V^{H}8$) or little to loose ($V^{L}8$), much would be lost in expectation due to discounting while waiting. So the agent would be more prone to investing before he is certain it is a good project (hence q9). And the belief about the odds of the project being a high value project does not need to be as high for the agent to strictly prefer to wait (so q9). Therefore the probability of hitting the upper bound before hitting the lower bound increases. The likelihood of an inefficient positive cascade goes up and the likelihood of an inefficient negative cascade goes down.¹⁵

As the prior expected value of the project goes up due to an increase in q^* , the upper bound q and the lower bound \underline{q} are unaffected, by (6) and (5). Being closer to the upper bound to begin with, the agents require less evidence in their learning process to strictly prefer investment. Hence they are more likely to invest when the prior improves.

PROPOSITION 3: As t e prior expected value increases q^*8 or $V^{L}8$ or $V^{L}8$) it becomes more likelY t at all a ents wit an option undertake t e probect It becomes less likelY t at t ere is an investment collapse w en t e true value is i Prob INC)9 It becomes more likelY t at t ere is an investment boom w en t e true value is low Prob IPC)8

Proof: Appendix C.

¹⁵ In an exogenous-timing herding framework Welch (1992) shows that as the prior expected value from investment goes up, there is a greater chance that society ends up in a positive cascade since early movers are more likely to invest.

62 Discountin :

Discounting doesn't play a role in exogenous-timing models. Examination of this issue requires an endogenous-timing model. The agent makes a choice between investing now or later. If the agent waits, he can learn by observing other people's actions, however the payoff gets discounted. All else constant, as people get more patient (* 8), they will be more willing to wait. Since waiting induces learning, one might be tempted to conclude that higher * would be associated with a smaller probability of an erroneous mass behavior. However this is not the case. In fact the probability of an inefficient negative cascade goes up. Chamley and Gale (1994) show that for *=1there is a weakness of the investment process in the direction of underinvestment. Proposition 4 extends this result to comparative statics over the whole range of *.

PROPOSITION 4: As a ents become more patient *8) it becomes more likelY t at a ents do not undertake t e investment probect It becomes more likelY t at t ere is an investment collapse Prob INC)8 w en t e true value is i It becomes less likelY t at t ere is an investment boom Prob IPC)9 w en t e true value is low

Proof:

The probability of an inefficient negative cascade goes up as * goes up,

$$\frac{dProb \ INC)}{d\delta} = \left(\mathbf{I} \cdot Prob \ INC\right) \frac{2\varphi^{H} e^{2\varphi^{H} \ln \mathbf{I} \cdot \delta}}{\mathbf{I} \cdot \delta \left(\mathbf{I} \cdot e^{2\varphi^{H} \ln \mathbf{I} \cdot \delta}\right)} > 0$$
(24)

On the other hand, the probability of an inefficient positive cascade goes down as * goes up.

$$\frac{dProb \ IPC)}{d\delta} = -Prob \ IPC) \frac{2\varphi^{L} e^{2\varphi^{L} \ln I - \delta}}{I - \delta \left(I - e^{2\varphi^{L} \ln I - \delta}\right)} < 0$$
(25) ~

An increase in * has a two effects. The first effect is through the rate of information flow 8 As agents get more patient, at the ongoing information flow, they would strictly prefer to wait. So the rate of information flow goes down such that people are just indifferent between waiting and investing.¹⁶

However this first effect has no influence on the probability of inefficient cascades in this framework. When the true value of the project is high $V=V^{H}$, a weaker information flow implies a weaker drift velocity :^H which simply increases the likelihood of a negative cascade. However at the same time the weaker information flow decreases the noise $(F^{2})^{H}$ in the learning process. Each observation will have a smaller influence on the updating process. This reduces the likelihood of a negative cascade. And these two opposing effects exactly counterbalance each other. 8 cancels out from the probability of inefficient cascade (see equations (21) and (23)). The indirect effect through the information flow is therefore nullified. The spirit of the story is the same for the case when $V=V^{L}$.

The second effect of an increase in * is through the upper bound. A higher * yields a higher upper bound q leaving the starting point and the lower bound unchanged. Since investors are more patient, they are willing to wait until they are almost certain about the project before they buy. This makes an inefficient negative cascade more likely, and an inefficient positive cascade less likely.

This comparative statics result suggests that financial markets might be more prone to inefficient collapses than real markets. Once an investment order is given, the payoff can be collected only at the end of the period. Keeping the rate of time preference constant, as the time to process investment decisions increases so does the distance between the time periods in the model, leading to a lower *. In financial markets, the administrative and technological systems may be faster to react to

¹⁶See Chamley (2004) for a simple two period two agent example. If $V=V^H$, both people have an option. If the $V=V^{L_1}$ only one agent has an option. In equilibrium, the agent if not invested in the first period would invest in the second period only if he observes investment in the first period. When * goes up, the equilibrium probability if investment in the first period goes down, making an investment collapse more likely even if the true value is high.

agents investment decisions than in real markets. Hence in financial markets the relevant * would be larger than in real markets leading to a higher likelihood of an inefficient collapse.

63 QualitY of Information:

The leading model of Bikhchandani, Hirshleifer and Welch (1992) shows that as signal quality goes up, inefficient negative and positive cascade probabilities go down. The effect is monotonic. Here, this not the case. An increase in the signal quality does of course unambiguously improve the expected value of the game to the market participants.¹⁷ But the probabilities of inefficient cascades may go up or down depending on the parameter values. Result 1 in Bikhchandani, Hirshleifer and Welch (1992) is closely related. It shows that all agents after the second are better off when the first agent's signal quality (expertise) is slightly decreased. This results in more information for later individuals as it decreases the probability that a cascade forms after just two individuals. A related issue arises here when the starting belief is close to one of the boundaries.

To understand the role of signal quality in this framework, first notice that agents who receive an investment option would all undertake the investment if there were no social learning. It is through social learning that the possibility of an investment collapse arises. The increase in signal quality affects the outcome of the game through two channels; i) *Self-confidence*: It increases the confidence of the agent in his own signal. Keeping the level of signal quality of the rest of the people constant, as the signal quality of the agent goes up, the agent is more likely to undertake the project, hence Prob(INC)9 and Prob(IPC)8. ii) *Confidence in observational learnin* : It increases the confidence of the agent in observational learning since each individual has a high quality signal. Now keeping the signal quality of the agent constant, as the signal quality of the rest of the players increases the agent

¹⁷See equations (3) and (4).

becomes more likely not to undertake the project, hence Prob(INC)8 and Prob(IPC)9. These two channels with opposing forces can be examined below.

Let us first examine the probability of an inefficient negative cascade. Equation (20) can be rewritten as:

$$\frac{Prob \ INC) = 1 - \frac{I - e^{2\phi^H} \ \underline{w} - w_0)}{H - e^{2\phi} \ \underline{w} - w_0}$$
(26)

From (14) and (15) notice that w and \overline{w} are independent of R. So,

$$\frac{d\operatorname{Pr}ob(INC)}{d\psi} = \frac{\Box \partial \operatorname{Pr}ob(INC) \partial w_0}{\Box \partial w_0} \Box + \frac{\Box \partial \operatorname{Pr}ob(INC) \partial \phi}{\partial \phi^H} \Box$$
(27)

The first term relates to the first channel; self-confidence. It is the effect of R on the probability of an inefficient negative cascade through the agents's belief before the observational learning starts (w_0). It is positive by Claim C3 in Appendix C.¹⁸ The second term relates to the second channel; confidence in observational learning. It is negative by Claim C1 and C4 in Appendix C. Therefore there are two forces working in opposite directions.

Let us now examine the probability of an inefficient positive cascade. Rewrite (22) as,

$$Prob \ IPC) = \frac{I - e^{2\varphi^L} \ \underline{w} - w_0)}{I - e^{2\varphi^L} \ \underline{w} - \overline{w})}$$
(28)

¹⁸This is consistent with the discussion in the previous paragraph since an increase in R represents a deterioration in signal quality.

So,

$$\frac{d \operatorname{Pr} ob(IPC)}{d\psi} = \frac{\partial \operatorname{Pr} ob(IPC)}{\partial w_0} + \frac{\partial \operatorname{Pr} ob(IPC)}{\partial \phi}$$

$$(29)$$

The first term is negative by Claim C5 in Appendix C. It relates to the first channel. The second term relates to the second channel. It is positive by Claim C2 and Claim C6 in Appendix C. Hence there are two opposing effects.

Proof: Appendix C

Proposition 5 is proven in two steps. The first step proves that $\frac{d \operatorname{Pr}ob(INC)}{d\psi} > 0$, when $w_0 6 w$ and $\frac{d \operatorname{Pr}ob(INC)}{d\psi} < 0$ when w_0 is not to close to either of the bounds, $w << w_0 << \overline{w}$. The second step proves that $\frac{d \operatorname{Pr}ob(IPC)}{d\psi} < 0$, when $w_0 6 \overline{w}$. $\frac{d \operatorname{Pr}ob(IPC)}{d\psi} > 0$ when w_0 is not to close to either of the bounds, $w << w_0 << \overline{w}$. Depending on the initial belief of the agent with an option, the effect of an increase in signal quality through confidence in observational learning can dominate the effect through self-confidence. If the agent does not have a strong initial belief (such that w_0 is not too close to either of the bounds) the social learning channel becomes more important in determining the direction of the effect of signal quality on the outcome of the game. An increase in signal quality can lead to an increase in the probability of inefficient herding. Investment is stochastic by the very nature of the game. Even when the true value of the project is high, it is possible to get a few bad draws in a row. In such a case, when the signal quality is high, the agent will heavily update his beliefs possibly leading to an

investment collapse.¹⁹ If however the signal quality were lower, the agent would need to collect more evidence before he strictly preferred to wait.²⁰

7. Conclusion

Knowledge of the direction and the magnitude of comparative statics results on the probability of a collapse is essential in herd manipulation. The pricing decision of a firm introducing a new technology, the advertising policy affecting the signal quality may be some of the key elements in manipulating the outcome of the social learning game. In financial markets, one of the objectives of regulatory bodies may be to reduce the probability of sudden crashes.²¹ While the tools available to the regulatory body for herd manipulation are typically restricted there is some room for relevant regulation. Accounting standards affect the signal quality, transaction taxes affect the expected value, the closing and opening times as well as the time of delay for payments of the payoffs affect discounting.

The advantage of analyzing the likelihood of inefficient cascades arises when there are externalities from the market to society at large. In these cases looking at the ex-ante utility of the players directly involved in the game insufficient for welfare analysis. For example, bank panics, capital flight and stock market crashes have external consequences which may induce a social planner

¹⁹On the other hand, naturally if signal quality is high, it would be less likely to have bad draws when the true value is high.

²⁰As the signal quality goes up, it is more likely that the first movers pick the correct choice and the confidence in observational learning increases. But this implies that the agent will be more likely to go with the "trustworthy" crowd which is bad news if the early movers happen to have picked the incorrect choice. If some agents' signal quality is unboundedly high then there is no chance of this occurring, see Rogers (2005). Also see De Vany and Lee (2001). Nelson (2002) looks at a related but different aspect of signal quality. The simulation results indicate that in a changing environment, the *frequencY* of herding is non-monotone in signal quality.

²¹Avery and Zemsky (1998) show that herd behavior can lead to a significant short-run mispricing of financial assets. See Dremann, Oechssler and Roider (2005) for an experimental analysis of Avery and Zemsky (1998).

to place a greater weight on inefficient negative cascades than an individual investor. In other markets the party designing the structure of the market may not have an incentive to weigh all market participants equally. In the IPO market, for example, the features of the market are not controlled by a central planner, but rather by the firms offering companies for public sale. These companies may try to increase the probability of a positive cascade. Results on the probabilities of inefficient outcomes are a potentially useful building block for welfare and policy analysis in markets with such external effects.

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APPENDIX

Appendix A:

Claim A1: $J^H > O$ w ere $J^H = \Box \psi - I - I + \phi ln \frac{\psi + \phi}{1 + \phi} \Delta rn^H$.

Proof: Define $f(\psi) = \bigcup_{i=1}^{n} \psi \cdot I \cdot I + \phi \ln \frac{\psi + \phi}{1 + \phi}$ Note t at f(I) = O

Since $f \quad \psi$ = $\frac{\psi - I}{\psi + \phi} < 0$ Y $f \mathsf{R}$ >0 for $O < \mathsf{R} < I$ So $\mu^H > O$

Claim A2: $J^L < 0 \quad w \quad ere \quad J^L = \Box \psi - I - \psi + \phi) ln \frac{\psi + \phi}{1 + \phi} \Delta rn^H.$

Proof: Define $f(\psi) = \Box \psi - I - \psi + \phi \ln \psi + \phi \Box$ Note t at f(I) = O

Since $f'(\psi) = -\ln \frac{\psi + \phi}{1 + \phi} > 0$ Y $f \mathsf{R} > 0$ $O \operatorname{for} O < \mathsf{R} < I So$ $\mu^L < O$.

Appendix B:

Lemma B1: Let $w_t(\lambda)$ be a Brownian Motion wit absorbin boundaries as defined in I4) and I5) : and F^2 as defined in I1) and I1) and wit startin point $w_T \in (\underline{w}, \overline{w})$ Let \tilde{w}_t be anot er process wit t e same form and parameters as w_t up to some possibly stoc astic time $\tau > T$ at w ic time t e parameter λ is replaced by λ' , w ic may also be stoc astic Bot $w_t(\lambda)$ and \tilde{w}_t Yield t e same probabilities of ittin t e boundaries 2I) and 23)

Proof: Define $b(\tau, w_{\tau}, \lambda')$ as t e boint p d f of τ , w_{τ} and λ' conditional on not ittin eit er boundar? in $t \leq \tau$. Define $P_{w_{\tau}(\lambda) \to \overline{w}}$ as t e probabilit? startin from w_{T} t at process its t e boundar? \overline{w} before \underline{w} . Since $w_{t}(\lambda)$ is a standard Brownian Motion $P_{w_{0}(\lambda) \to \overline{w}}$ is iven b?

$$P_{w_{0}(\lambda)\rightarrow\overline{w}} = I \cdot \frac{\Upsilon_{\square}}{e} e^{\frac{-2I.w}{\sigma^{2}}} - e^{\frac{-2I.w}{\sigma^{2}}} \int_{\square}^{\square} e^{\frac{-2I.w}{\sigma^{2}}} e^{\frac{-2I.w}{\sigma^{2}}}} e^{\frac{-2I.w}{\sigma^{2}}} e^{\frac{-2I.w}{\sigma^{2}}}} e^{\frac{-2I.w}{\sigma^{2}}} e^{\frac{-2I.w}{\sigma^{2}}} e^{\frac{-2I.w}{\sigma^{2}}} e^{\frac{-2I.w}{\sigma^$$

and $P_{w_t(\lambda)\to\underline{w}} = 1 - P_{w_t(\lambda)\to\overline{w}}$. *T* ese depend on 8 only *t* rou *t* e ratio μ/σ^2 . Hence *t* e probabilities of $w_t(\lambda)$ ittin *t* e boundaries do not depend on 8 Alt ou *t* e date τ as no special relevance to

t is process we can still decomposed t is probabilitY into t e probabilitY t at it transitions before or at τ and t e probabilitY it transitions after τ :

$$P_{w_{0}(\lambda) \to \bar{w}} = P_{w_{0}(\lambda) \to \bar{w} \not\models \leq \tau} + \frac{\gamma}{2} 1 - P_{w_{0}(\lambda) \to \bar{w} \not\models \leq \tau} - P_{w_{0}(\lambda) \to \underline{w} \not\models \leq \tau} \int_{\tau} \int_{w_{\tau}(\lambda)} P_{w_{\tau}(\lambda) \to \bar{w}} b(\tau, w_{\tau}, \lambda') \cdot d\tau \cdot dw_{\tau} \cdot d\lambda'$$

$$(31)$$

W ile we know t e left- and side of t is t e formulas for t e conditional probabilities and p d f s on t e ri t- and side are unknown However since \tilde{w}_t starts off as t e same process we can similarlY decompose its probabilitY as

$$P_{\bar{w}_{0}\to\bar{w}} = P_{w_{0}(\lambda)\to\bar{w}\not\models\leq\tau} + \underbrace{\Upsilon 1 - P_{w_{0}(\lambda)\to\bar{w}\not\models\leq\tau} - P_{w_{0}(\lambda)\to\underline{w}\not\models\leq\tau}}_{f \int_{\tau} \int_{\tau} \int_{w_{\tau}(\lambda')\to\bar{w}} b(\tau, w_{\tau}, \lambda') \cdot d\tau \cdot dw_{\tau} \cdot d\lambda'}$$
(32)

Here bot t e left and ri t- and side probabilities are unknown Nevert eless since it is t e same process up to τ t ese conditional probabilities and p d f s are t e same as in 3I) wit t e exception of t e continuation probabilities in t e inter rals Note owever t ese are simply t e probabilities for Brownian Motion startin from w_{τ} wit parameter λ' and ence for eac potential realiliation of w_{τ} and λ' t e probability can be found from 30) by substitutin w_{τ} for w_0 . As before λ' cancels out from t ese probabilities T erefore eac $P_{w_{\tau}(\lambda') \to \bar{w}}$ in equation 32) is equal to t e correspondin $P_{w_{\tau}(\lambda) \to \bar{w}}$ in 3I) and ence $P_{w_0(\lambda) \to \bar{w}} = P_{\bar{w}_0 \to \bar{w}}$. T e same ar ument s ows t at $P_{w_0(\lambda) \to \bar{w}} = P_{\bar{w}_0 \to \bar{w}}$, w ic completes t e proof of t e lemma

Proposition B1: T e equilibrium of t e ame wit anY finite set \bullet of possible contin encY tri er points w ic contains \overline{q} and q will Yield t e same transition probabilities as t e baseline model

Proof: From t e baseline model w $ere \Gamma = \{\underline{q}, \overline{q}\}$ add one contin encY tri er point q'. If q > q or q' < q t en t e state q' would never be reac ed in t e baseline equilibrium. We can construct a parallel equilibrium w ere no a ent c ooses to ave a contin encY tri ered at q'. Hence t e edition of q' will not c an e t e transition probabilities.

If $q' \in (\overline{q}, \overline{q})$ t en some a ents maY c oose to set contin encY tri ers t ere Let $\pi(q_T, t)$, encefort B be t e probabilitY t at an individual a ent c ooses to set a contin encY tri er at q'. T is maY be eit er to buY or to cancel an impendin order Note t at π maY depend on t since

for a iven number of impendin orders t e time remainin in t e period will determine t e rate of information flow durin t e rest of t e period w ic in tern influences t e expected value of waitin T e same ar ument used for λ implies t at B<I If q' is a buY tri er and B=I t en eac individual would prefer to wait since $q' < \overline{q}$. If it is a wait tri er and B=I t en eac individual would prefer to buY since q' > q.

Moreover if t e a ents are usin q' as a buY tri er t en rBn^H must be finite for all contin encies w ic maY be it wit non-ne li ible probabilitY If not t en if t e contin encY is tri ered at anY t<T+I-g t e true value of n and ence V would be revealed wit certaintY bY t e end of t e period Since $q' < \overline{q}$ eac individual would prefer to wait w en t e state will be revealed wit certaintY

So eit er t e addition of q' as no effect on t e outcome in t e period B=0) or in equilibrium eac individual will be indifferent between usin it as a tri er or not and t e number of a ents wit outstandin buY orders at eac contin encY tri er point will be drawn from a Poisson distribution wit finite mean So t e addition of t e contin encY will cause 8 to c an e w en it is tri ered But bY Lemma CI t is new process as t e same transition probabilities as t e ori inal process Iteratin t e ar ument allows us to add anY finite number of contin encY tri er points to t e set • wit out alterin t e transition probabilities

Appendix C:

Claim C1:
$$\frac{d\varphi^{H}}{d\psi} > 0 \quad w \quad ere \quad \frac{d\varphi^{H}}{d\psi} = \frac{-2\psi + 2 + (1+\psi + 2\phi)\ln\frac{\psi + \phi}{1+\phi}}{(\psi + \phi)(1+\phi) \begin{bmatrix} \ln\frac{\psi + \phi}{1+\phi} \end{bmatrix}^{3}}$$

Proof: Define $f(\psi) = -2\psi + 2 + (1 + \psi + 2\phi) \ln \frac{\psi + \phi}{1 + \phi}$ Note t at f(I) = O

And $f(\psi) = -2 + \frac{1+\psi+2\phi}{\psi+\phi} + \ln \frac{\psi+\phi}{1+\phi}$ Note t at f'(1) = 0

$$f''(\psi) = \frac{\psi - 1}{(\psi + \phi)^2} < 0 \quad Hence \quad f'(\psi) > 0 \text{ for } O < \mathsf{R} < I \text{ So } f(\mathsf{R}) < 0 \quad so \quad \frac{d\phi''}{d\psi} > 0$$

Claim C2:
$$\frac{d\varphi^{L}}{d\psi} > 0 \quad w \quad ere \quad \frac{d\varphi^{L}}{d\psi} = \frac{-2\psi + 2 + (1 + \psi + 2\phi)\ln\frac{\psi + \phi}{1 + \phi}}{(\psi + \phi)^{2} \left[\ln\frac{\psi + \phi}{1 + \phi}\right]^{3}}$$

Appendix-3

Proof: $\frac{d\varphi^{L}}{d\psi}$ and $\frac{d\varphi^{H}}{d\psi}$ ave t e same numerator In Lemma A3 it is s own t at t e numerator is

ne ative Since t e denominator is ne ative as well $\frac{d\varphi^L}{d\psi} > 0$

Claim C3: *T* e first term of 27) is positive $\frac{\partial \operatorname{Pr}ob(INC) \partial w_0}{\partial w_0 \partial \psi} > 0$

Proof:
$$\frac{\partial \operatorname{Pr}ob(INC)}{\partial w_0} = -\frac{2\varphi^H e^{2\varphi^H}(\underline{w}-w_0)}{1 - e^{2\varphi^H}(\underline{w}-\overline{w})} < 0 \quad since \ (1 - e^{2\varphi^H}(\underline{w}-\overline{w})) > 0 \quad And \ \frac{\partial \psi}{\partial \psi} = -\frac{1}{\psi} < 0.$$

$$\mathbf{Claim} \ \mathbf{C4:} \frac{\partial \operatorname{Pr}ob(INC)}{\partial \varphi^{H}} < 0 \ w \ ere \ \frac{\partial \operatorname{Pr}ob(INC)}{\partial \varphi^{H}} = -\frac{I \cdot e^{2\varphi^{H} \ \underline{w} \cdot w_{0}}}{I \cdot e^{2\varphi^{H} \ \underline{w} \cdot \overline{w}}} \underbrace{\frac{\gamma}{1 - e^{2\varphi^{H} \ \underline{w} - \overline{w}}}}_{1 - e^{2\varphi^{H} \ \underline{w} - \overline{w}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{H} \ \underline{w} - w_{0}}}{1 - e^{2\varphi^{H} \ \underline{w} - w_{0}}} \underbrace{\frac{\gamma}{1 - e^{2\varphi^{H} \ \underline{w} - w_{0}}}}_{1 - e^{2\varphi^{H} \ \underline{w} - w_{0}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{H} \ \underline{w} - w_{0}}}{1 - e^{2\varphi^{H} \ \underline{w} - w_{0}}} \underbrace{\frac{\gamma}{1 - e^{2\varphi^{H} \ \underline{w} - w_{0}}}}_{1 - e^{2\varphi^{H} \ \underline{w} - w_{0}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{H} \ \underline{w} - w_{0}}}{1 - e^{2\varphi^{H} \ \underline{w} - w_{0}}} \underbrace{\frac{\gamma}{1 - e^{2\varphi^{H} \ \underline{w} - w_{0}}}}_{1 - e^{2\varphi^{H} \ \underline{w} - w_{0}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{H} \ \underline{w} - w_{0}}}{1 - e^{2\varphi^{H} \ \underline{w} - w_{0}}} \underbrace{\frac{\gamma}{1 - e^{2\varphi^{H} \ \underline{w} - w_{0}}}}_{1 - e^{2\varphi^{H} \ \underline{w} - w_{0}}} = \underbrace{\frac{\gamma}{1 - e^{2\varphi^{H} \ \underline{w} - w_{0}}}}_{1 - e^{2\varphi^{H} \ \underline{w} - w_{0}}} \underbrace{\frac{\gamma}{1 - e^{2\varphi^{H} \ \underline{w} - w_{0}}}}_{1 - e^{2\varphi^{H} \ \underline{w} - w_{0}}}}$$

Proof: T e term inside t e brackets is positive Examine t e properties of t e followin function Let $(x) = \frac{2(w-x)e^{2\phi^{n}} w^{-x}}{1-e^{2\phi^{n}} w^{-x}}$ w ere x > w T en notice t at t e term inside t e brackets is equal to $x = (w_{0})f \frac{d}{dx} = 0$ t $en x = (w_{0})f = 0$ and $\frac{\partial Prob(INC)}{\partial \phi^{n}} < 0$ $\frac{d}{dx} = \frac{2e^{2\phi^{n}}(w-x)}{(1-e^{2\phi^{n}}(w-x))^{2}} \left(e^{2\phi^{n}}(w-x) - 1 - 2\phi^{n}}(w - x)\right)$ Let $|i| = 2\phi^{n}(w-x)$ w ere |i| < 0 for $x0 = w_{0}$ w) T e term in t e parent esis is t en equal $f(|i|) = e^{it} - 1 - ii$ f = li=0 = 0 And $f'(|i|) = e^{it} - 1 < 0$ for all li < 0 Hence $\frac{d}{dx} = \frac{d}{dx} = 0$ T erefore $\frac{\partial Prob(INC)}{\partial \phi^{n}} < 0$ ~

Claim C5: *T* e first term of 21) is ne ative $\frac{\partial \Pr{ob(IPC)} \partial w_0}{\partial w_0} < 0$.

Proof:
$$\frac{\partial \operatorname{Pr}ob(IPC)}{\partial w_0} = \frac{2\varphi^L e^{2\varphi^L (\underline{w}-w_0)}}{1-e^{2\varphi^L (\underline{w}-\overline{w})}} > 0 \text{ since } n^L < O \text{ and } (1-e^{2\varphi^L (\underline{w}-\overline{w})}) < O \text{ And } \frac{\partial w_0}{\partial \psi} = -\frac{1}{\psi} < 0.$$

Appendix-4

Claim C6:
$$\frac{\partial \operatorname{Pr}ob(IPC)}{\partial \varphi^{L}} > 0 \quad w \quad ere \quad \frac{\partial \operatorname{Pr}ob(IPC)}{\partial \varphi^{L}} = \frac{I - e^{2\varphi^{L}} \underline{w} - \overline{w}_{0}}{I - e^{2\varphi^{L}} \underline{w} - \overline{w}_{0}} + \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - \overline{w}_{0}}{1 - e^{2\varphi^{L}} \underline{w} - \overline{w}_{0}} - \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}} + \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} + \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} + \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} + \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} = \frac{2(\underline{w} - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0}}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}}} \underline{w} - w_{0}} \underline{$$

Proof: T e term inside t e brackets is positive Examine t e properties of t e followin function

Let
$$(x) = \frac{2(\underline{w} - x)e^{2\varphi^L} \underline{w} - x)}{1 - e^{2\varphi^L} \underline{w} - x)} w$$
 ere $x > w$ t en notice t at t e term inside t e brackets is equal to

 $\underbrace{\Upsilon}_{\leq} (w) - (w_0) f \quad If \frac{d(x)}{dx} > 0 \quad t \quad en \quad \frac{\partial \operatorname{Pr} ob(IPC)}{\partial \varphi^L} > 0 \quad since \ w > w_0$

$$\frac{d(x)}{dx} = \frac{2e^{2\varphi^{L}(w-x)}}{(1-e^{2\varphi^{L}(w-x)})^{2}} \left(e^{2\varphi^{L}(w-x)} - 1 - 2\varphi^{L}(w-x)\right)$$

Let $li = 2\varphi^{L}(\underline{w} - x) w$ ere li > 0 for $x\mathbf{0} w_{0} w$)

T e term in t e parent esis is t en equal
$$f(li) = e^{li} - 1 - li$$

$$f \ li=0 = 0$$
 And $f'(li) = e^{li} - 1 > 0$ for all $li>0$ Hence $\frac{d(x)}{dx} > 0$ T erefore $\frac{\partial \Pr ob(IPC)}{\partial \varphi^L} > 0$

 \sim

Proof of Proposition 3 (Prior Expected Value):

T e prior expected value increases due to $q*8 \text{ or } V^H 8 \text{ or } V^L 8$ First notice t at $(I - e^{2\varphi^{H_{ln}I-\delta}}) > 0$ since $n^H > 0$ and $(I - e^{2\varphi^{L_{ln}I-\delta}}) < 0$ since $n^L < 0$

T e comparative statics are as follows

$$\frac{d \operatorname{Pr} ob(INC)}{dq^{*}} < 0 \quad and \qquad \frac{d \operatorname{Pr} ob(IPC)}{dq^{*}} > 0$$
$$\frac{d \operatorname{Pr} ob(INC)}{dV^{H}} < 0 \quad and \qquad \frac{d \operatorname{Pr} ob(IPC)}{dV^{H}} > 0$$
$$\frac{d \operatorname{Pr} ob(INC)}{dV^{L}} < 0 \quad and \qquad \frac{d \operatorname{Pr} ob(IPC)}{dV^{L}} > 0$$

$$\frac{dProb \ INC}{dq^{*}} = \frac{I - q^{*} q^{*} I - e^{2\varphi^{-ln} I - \delta}}{I - q^{*} q^{*} I - e^{2\varphi^{-ln} I - \delta}} and \frac{dProb \ IPC}{dq^{*}} = \frac{2\varphi^{-L} e^{2\varphi^{-L} \sum ln I - q^{*} - lnq^{*} + ln\psi - lnV^{H} + ln - V^{-V} f}}{I - q^{*} q^{*} I - e^{2\varphi^{-ln} I - \delta}}$$

Comparative statics wit respect to V^{H}

$$\frac{dProb \ INC)}{dV^{L}} = \frac{2\varphi^{H} e^{2\varphi^{H} \sum_{i=1}^{n} I - q^{*} - \ln q^{*} + \ln \psi - \ln V^{H} + \ln - V^{L} \frac{V}{f}}}{I - e^{2\varphi^{H} \ln I - \delta}} \ and \frac{dProb \ IPC}{dV^{H}} = \frac{2\varphi^{L} e^{2\varphi^{L} \sum_{i=1}^{n} I - q^{*} - \ln q^{*} + \ln \psi - \ln V^{H} + \ln - V^{L} \frac{V}{f}}}{I - e^{2\varphi^{L} \ln I - \delta}} \ V^{H}$$

Comparative statics wit respect to V^L

$$\frac{dProb \ INC)}{dV^{L}} = \frac{2\varphi^{H} e^{2\varphi^{H} \sum \ln I - q^{*} \right) - \ln q^{*} + \ln \psi - \ln V^{H} + \ln V^{L} y^{L}}}{I - e^{2\varphi^{H} \ln I - \delta}} and \ \frac{dProb \ IPC}{dV^{L}} = \frac{-2\varphi^{L} e^{2\varphi^{L} \sum \ln I - q^{*} \right) - \ln q^{*} + \ln \psi - \ln V^{H} + \ln V^{L} y^{L}}}{I - e^{2\varphi^{L} \ln I - \delta}} V^{L}$$

Proof of Proposition 5 (Signal Quality):

Step 1: $\frac{d \operatorname{Pr}ob(INC)}{d\psi} > O w en w_0 \mathbf{6} w \quad \frac{d \operatorname{Pr}ob(INC)}{d\psi} < 0 w en w_0 is not to close to eit er of t e bounds$

~

 $w << w_0 << w$

Proof:

$$i) \frac{d \operatorname{Pr} ob(INC)}{d\psi} > O w en w_0 6w$$

 w_0 is a function of q^* All ot er terms, $w, w, =^H$ and $F^2)^H$ in 20) are invariant of $q^* w_0 6 w$ is equivalent to $\ln \frac{q^*}{1-q^*} \rightarrow \ln(-V^L) - \ln(V^H) + \ln\psi$ W en $w_0 6wt$ e second term of 27) oes to liero T e

first term remains positive Hence $\frac{d \operatorname{Pr} ob(INC)}{d\psi} > 0 \ w \ en \ w_0 \mathbf{6} w$

Appendix-6

$$\frac{d \operatorname{Pr} ob(INC)}{d\psi} = \frac{\Box}{\Box} \frac{\partial \operatorname{Pr} ob(INC)}{\partial w_0} \frac{\partial w_0}{\partial \psi} = \frac{\Box}{\Box} \frac{\partial \operatorname{Pr} ob(INC)}{\partial \varphi^H} \frac{\partial \varphi}{\partial \psi} = \frac{\Box}{\Box} \frac{\partial \operatorname{Pr} ob(INC)}{\partial \varphi^H} \frac{\partial \varphi}{\partial \psi} = \frac{\Box}{\Box} \frac{\partial \varphi^H}{\partial \varphi} \frac{\partial \varphi^H}{\partial \psi} = \frac{\Box}{\Box} \frac{\partial \varphi^H}{\partial \psi} \frac{\partial \varphi^H}{\partial \psi} \frac{\partial \varphi^H}{\partial \psi} = \frac{\Box}{\Box} \frac{\partial \varphi^H}{\partial \psi} = \frac{\Box}{\Box} \frac{\partial \varphi^H}{\partial \psi} \frac{\partial \varphi^H}{\partial \psi} = \frac{\Box}{\Box} \frac{\partial \varphi^H}{\partial \psi} =$$

First examine

$$\frac{\partial \operatorname{Pr}ob(INC)}{\partial \varphi^{H}} = -\frac{I \cdot e^{2\varphi^{H} \underline{w} \cdot w_{0}}}{I \cdot e^{2\varphi^{H} \underline{w} - \overline{w}}} \frac{\Upsilon 2(\underline{w} - \overline{w})e^{2\varphi^{H} \underline{w} - \overline{w}}}{1 - e^{2\varphi^{H} \underline{w} - \overline{w}}} - \frac{2(\underline{w} - w_{0})e^{2\varphi^{H} \underline{w} - w_{0}}}{1 - e^{2\varphi^{H} \underline{w} - w_{0}}} \propto q^{2}$$

Let $(x) = \frac{2(\underline{w} - x)e^{2\varphi^{H}} + \underline{w} - x)}{1 - e^{2\varphi^{H}} + \underline{w} - x)} w$ ere x > w Notice t at x < 0 for x > w and $\frac{d(x)}{dx} > 0$

Pick *=** suc t at w) =
$$\frac{1}{2}$$
 (w₀) T en χ (w) - (w₀)/f = $-\frac{1}{2}$ (w₀) > 0

For **

$$\frac{\partial \operatorname{Pr}ob(INC)}{\partial \varphi^{H}} = \frac{I \cdot e^{2\varphi^{H}} \underline{w} \cdot w_{0}}{I \cdot e^{2\varphi^{H}} \underline{w} \cdot \overline{w}}} \frac{\Upsilon (\underline{w} - \underline{w}) e^{2\varphi^{H}} \underline{w} \cdot w_{0}}{4} \frac{\varphi^{2\varphi^{H}} \underline{w} \cdot$$

From Claim CI and C3

$$\frac{d \operatorname{Pr} ob(INC)}{d\psi} = \underbrace{\begin{array}{c} & 2\varphi^{H} \\ e^{2\varphi} \\ & & \\ \end{array}}_{I - e^{2\varphi^{H}} \\ & & \\ \Psi} \\ \psi \end{array} = \underbrace{\begin{array}{c} & 2\varphi^{H} \\ e^{2\varphi} \\ & & \\ \end{array}}_{H - e^{2\varphi^{H}} \\ & & \\ \end{array}}_{H - e^{2\varphi^{H}} \\ & & \\ \end{array}} \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & \partial \psi \end{array}\right]}_{U - e^{2\varphi^{H}} \\ & & \\ \end{array}}_{I - e^{2\varphi^{H}} \\ & & \\ \end{array}}_{W - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}\right]}_{V - \overline{W}} \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}\right]}_{U - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}\right]}_{W - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}\right]}_{W - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}\right]}_{W - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}\right]}_{W - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - 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\overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H - \overline{W}} \\ \xrightarrow{\left[\begin{array}{c} & \partial \varphi \\ & & \\ \end{array}}_{H -$$

$$\frac{Let us now factor out}{d = \frac{e^{2\varphi^{H}} \underline{w} \cdot w_{0}}{H}} > 0 \quad We \ t \ en \ ave$$

$$\frac{d \operatorname{Pr} ob(INC)}{d\psi} = \frac{e^{2\varphi^{H}} (\underline{w} - w_{0})}{I - e^{2\varphi^{H}} \underline{w} - w_{0}} + \frac{\partial \varphi^{H}}{\partial \psi} (\underline{w} - w_{0}) \leftarrow$$

$$\frac{\partial \psi}{\partial \psi} = \frac{\partial \varphi^{H}}{\partial \psi} = \frac{\partial \psi}{\partial \psi} =$$

T e multiplicative term outside *t* e parent esis is positive Inside *t* e parent eses $n^{H} > 0$ and $\frac{\partial \varphi^{H}}{\partial \psi} > 0$ $\overline{1} \quad \frac{bY}{Clai}$

Appendix-7

 $w) = 2 (w_0)$

for a bi enou * Hence $\frac{d \operatorname{Pr} ob(INC)}{d\psi} < 0$ for $w << w_0 << w$

Step 2:
$$\frac{d \operatorname{Pr} ob(IPC)}{d\psi} < O w \ en \ w_0 6w \ \frac{d \operatorname{Pr} ob(IPC)}{d\psi} > O w \ en \ w_0 is \ not \ to \ close \ to \ eit \ er \ of \ t \ e \ bounds$$

 $w < < w_0 << w$

Proof:

i)
$$\frac{d \operatorname{Pr} ob(IPC)}{d\psi} < O w \text{ en } w_0 \text{ for a function of } q^* \text{ All ot er terms } w, w, z^H \text{ and } F^2)^H \text{ in }$$

~

20) are invariant of $q^* w_0 6w$ is equivalent to

$$\ln \frac{q^*}{1-q^*} \to \ln(-V^L) - \ln(V^H) - \ln(1-\delta) + \ln\psi \quad W \text{ en } w_0 \delta w t \text{ e second term of } 21) \text{ oes to liero}$$

T e first term of 21) remains ne ative Hence $\frac{d \operatorname{Pr} ob(IPC)}{d\psi} < O$

ii)
$$\frac{d \operatorname{Pr} ob(IPC)}{d\psi} > 0$$
 w en w_0 is not to close to eit er of t e bounds $w << w_0 << w_0$

$$\frac{d \operatorname{Pr} ob(IPC)}{d\psi} = \frac{\partial \operatorname{Pr} ob(IPC)}{\partial w_0} \frac{\partial \psi_0}{\partial \psi} = \frac{\partial \operatorname{Pr} ob(IPC)}{\partial \phi} \frac{\partial \psi_0}{\partial \psi} = \frac{\partial \operatorname{Pr} ob(IPC)}{\partial \psi} = \frac{\partial \operatorname{Pr} ob(IP$$

First examine

$$\frac{\partial \operatorname{Pr}ob(IPC)}{\partial \varphi^{L}} = \frac{I - e^{2\varphi^{L}} \underline{w} - w_{0}}{I - e^{2\varphi^{L}} \underline{w} - \overline{w}}} \underbrace{\frac{\Upsilon 2(w - w)e^{2\varphi^{L}} \underline{w} - \overline{w}}{1 - e^{2\varphi^{L}} \underline{w} - \overline{w}}} - \frac{2(w - w_{0})e^{2\varphi^{L}} \underline{w} - w_{0})}{1 - e^{2\varphi^{L}} \underline{w} - w_{0}} \xrightarrow{\infty}_{off}$$

Let
$$x := \frac{2(\underline{w} - x)e^{2\varphi^L} \underline{w} - x)}{1 - e^{2\varphi^L} \underline{w} - x)} w$$
 ere $x > w$ notice t at $x > 0$ for $x > w$ and $\frac{d(x)}{dx} > 0$

Pick *=** suc t at w) =
$$\frac{1}{2}$$
 (w₀) T en $\stackrel{Y}{\leq}$ (w) - (w₀)/_f = $-\frac{1}{2}$ (w₀) < 0

Appendix-9

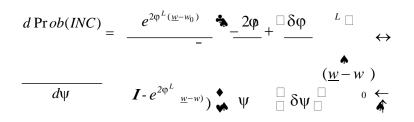
For **

$$\frac{\partial \operatorname{Pr}ob(IPC)}{\partial \varphi^{L}} = \frac{I \cdot e^{2\varphi^{L}} \underline{w} \cdot w_{0}}{I \cdot e^{2\varphi^{L}} \underline{w} \cdot \overline{w}}} \underbrace{\frac{\Upsilon(\underline{w} - w_{0})}{I - e^{2\varphi^{L}} \underline{w} \cdot \overline{w}}} \underbrace{\frac{\Upsilon(\underline{w} - w_{0})}{I - e^{2\varphi^{L}} \underline{w} - w_{0}}}_{\underline{\gamma}} \underbrace{\frac{\Upsilon(\underline{w} - w_{0})}{I - e^{2\varphi^{L}} \underline{w} - w_{0}}}_{\underline{\gamma}}$$

From Claim C2 and C4

$$\frac{d \operatorname{Pr} ob(INC)}{d\psi} = \overset{\bigstar}{\longrightarrow} \frac{2\varphi^{L}e^{2\varphi^{L}(\underline{w}-w_{0})}}{\psi I - e^{2\varphi^{L}(\underline{w}-w)}} \stackrel{\Box}{\longrightarrow} \delta\varphi^{L} \stackrel{\Box}{\longrightarrow} (w-w)e^{2\varphi^{L}(\underline{w}-w_{0})} \longleftrightarrow$$

Let us now factor out $\frac{e^{2\varphi^L} \underline{w} \cdot w_0}{I - e^{2\varphi^L} \underline{w} - \overline{w})}$ We t en ave



T e term outside t e parent esis is ne ative Inside t e parent eses $\varphi^{L} < 0$ and $\frac{\delta \varphi^{L}}{\delta \psi} > 0$ BY pickin q^* we can ave w_0 as lar e as we like and we can still maintain $w = \frac{1}{2} (w_0)$ for a i enou *

Hence $\frac{d \operatorname{Pr} ob(IPC)}{dw} > 0$ for $w << w_0 << w$